

TEMPORAL CORRELATION PATTERNS

Intersecting Joins, Streams, Events and Reactive Programming

Oliver Bračevac

Software Technology Group (Mira Mezini)

TU Darmstadt, Germany

bracevac@cs.tu-darmstadt.de

REBLS' 15

10/27/15 - Pittsburgh, PA, USA

REACTIVE PROGRAMMING?



FLAPJACK

FrTime

java.util.stream



Rx



CORRELATE | 'kɒrəleɪt, -rɪ-|

CORRELATE | 'kɒrəleɪt, -rɪ-|

- Have/establish a mutual relationship or connection, in which one thing affects or depends on another.

CORRELATE | 'kɒrəleɪt, -rɪ-|

- Have/establish a mutual relationship or connection, in which one thing affects or depends on another.
- “*We should **correlate** general trends in public opinion **with** trends in the content of television news.*”

(Oxford Dictionary of English)

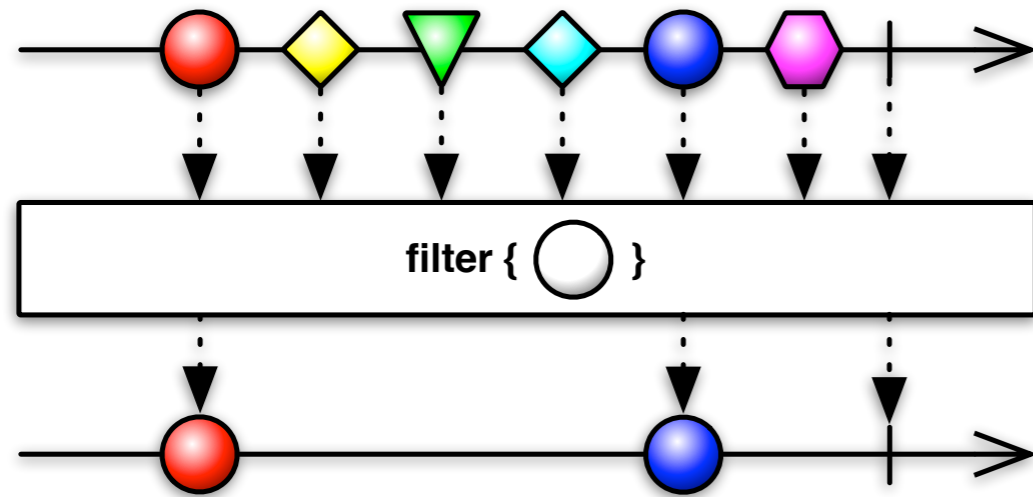
CORRELATE | 'kɒrəleɪt, -rɪ-|

- Have/establish a connection, in which one thing is related to another.
- *“We should correlate public opinion with trends in the news.”*

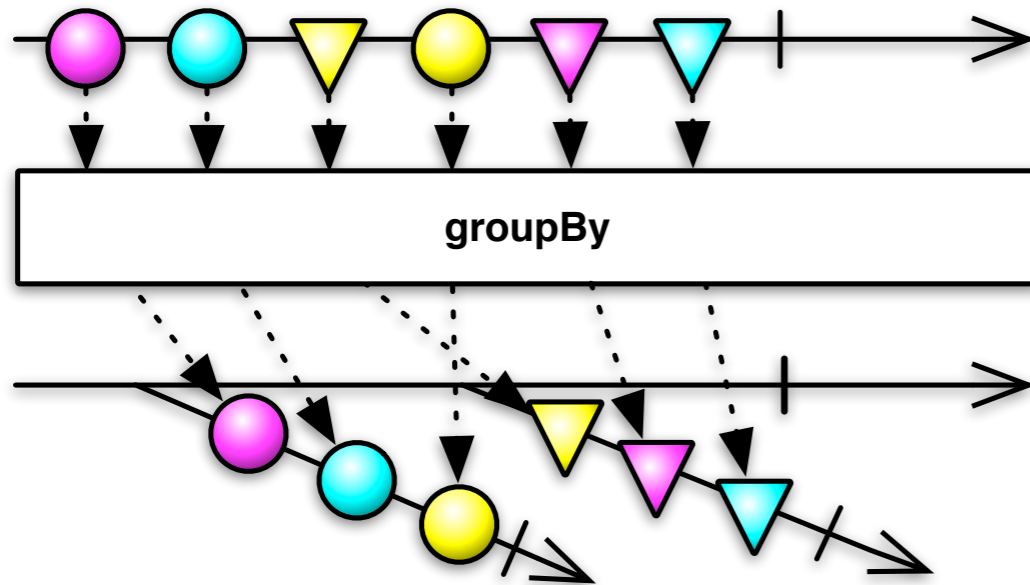
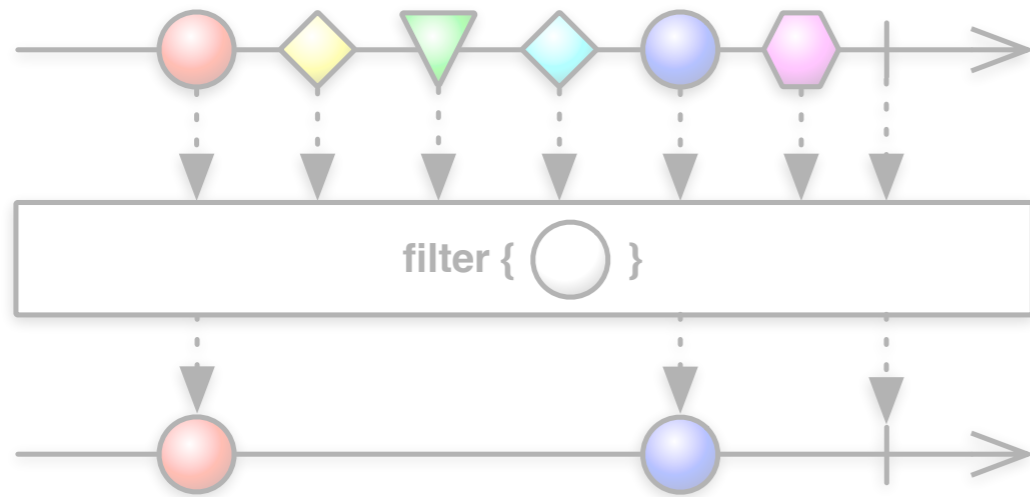
Reactive languages correlate data!

(Oxford Dictionary of English)

DATA CORRELATION IN RP

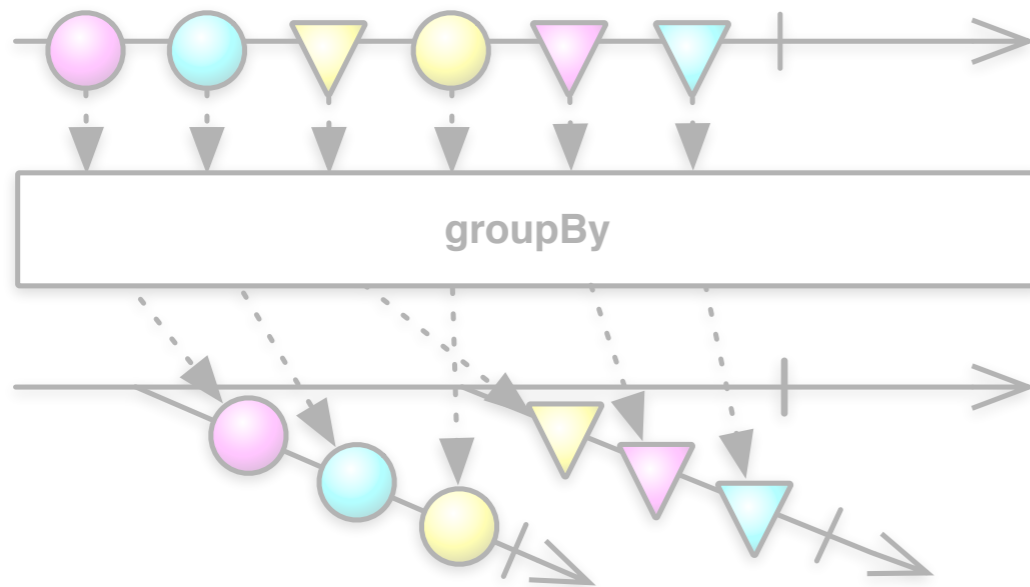
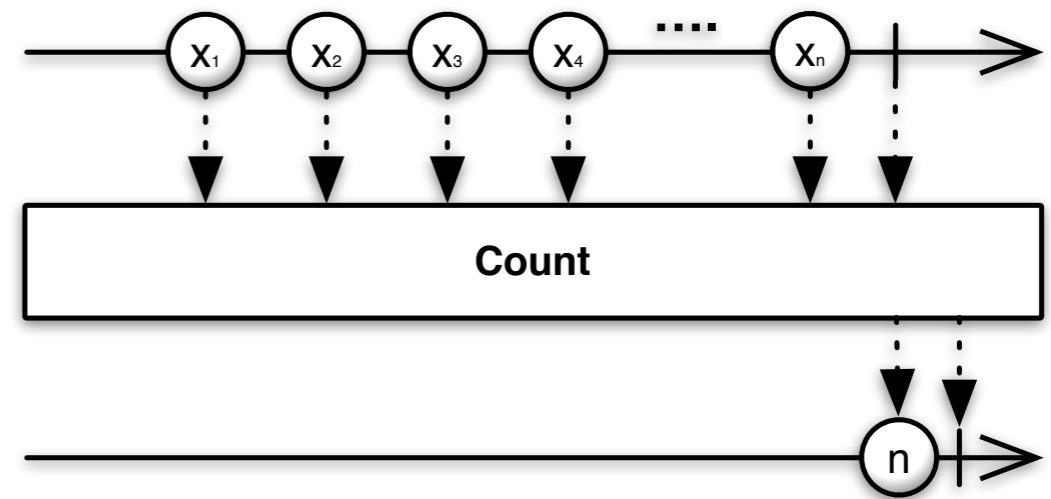
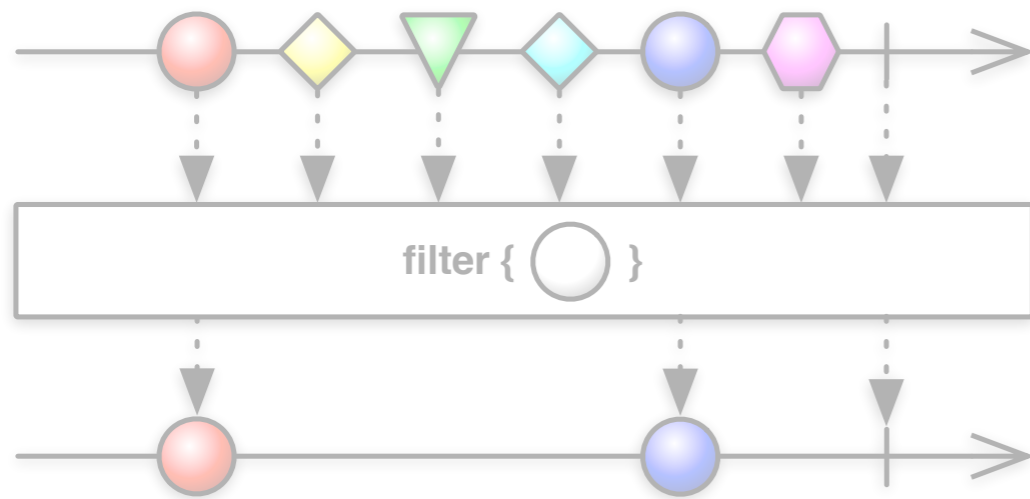


DATA CORRELATION IN RP



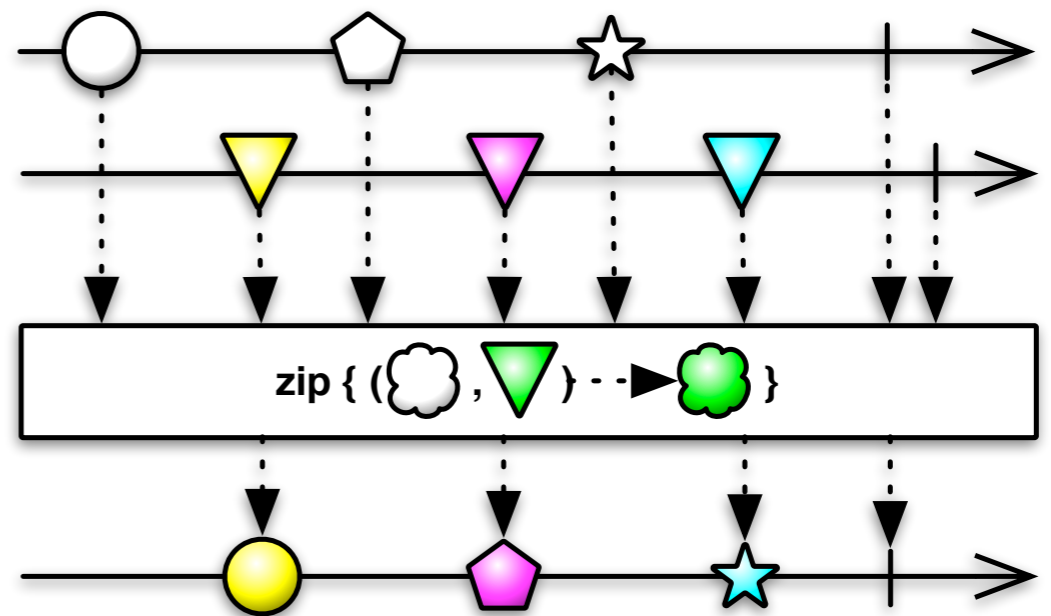
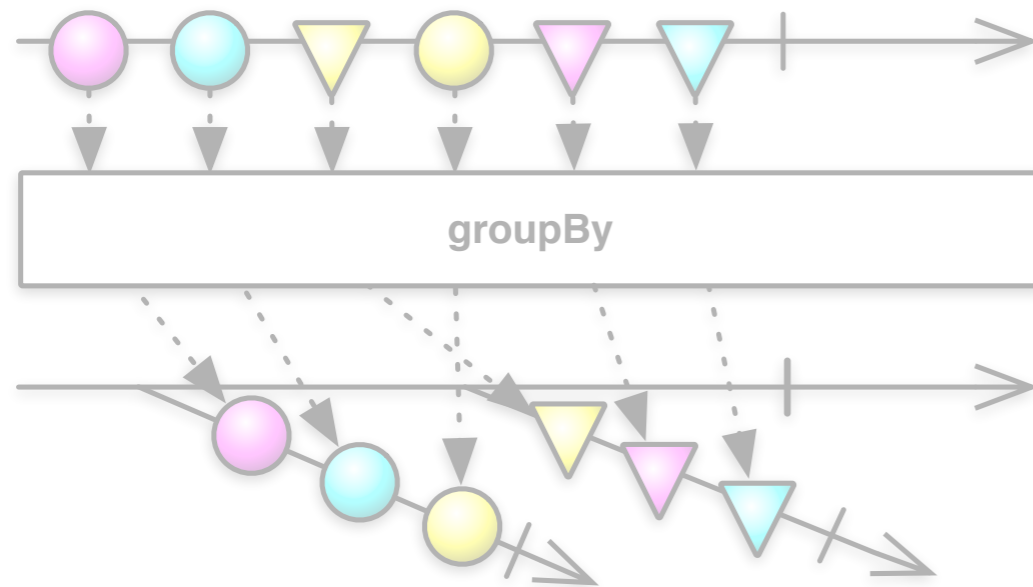
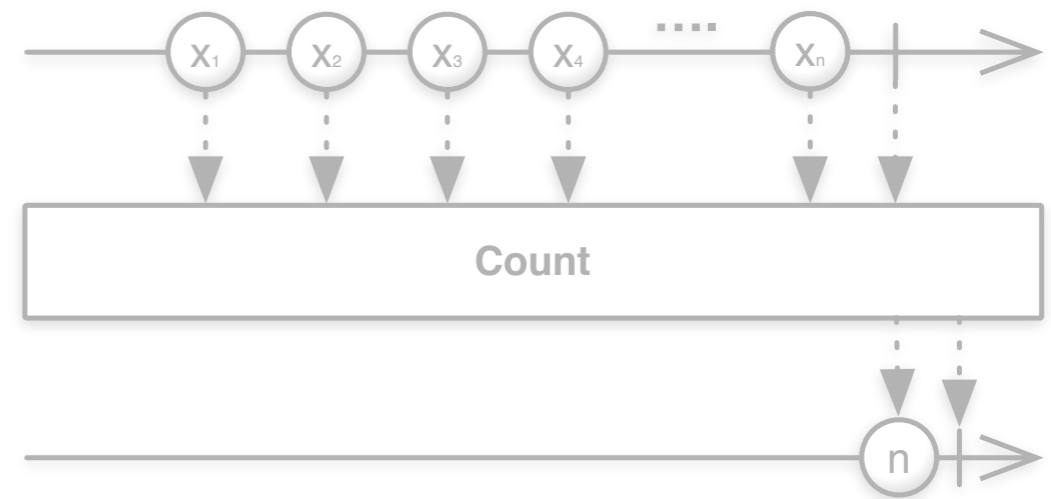
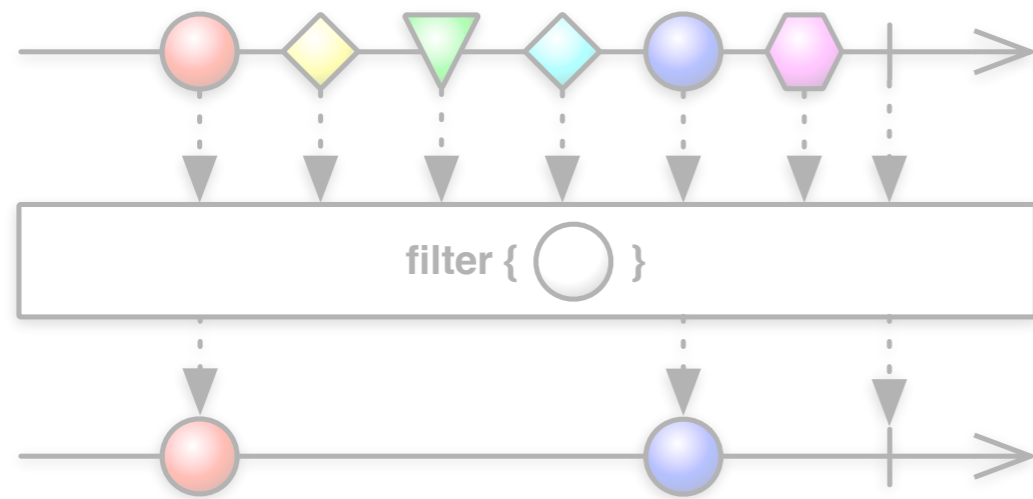
<http://reactivex.io>

DATA CORRELATION IN RP



<http://reactivex.io>

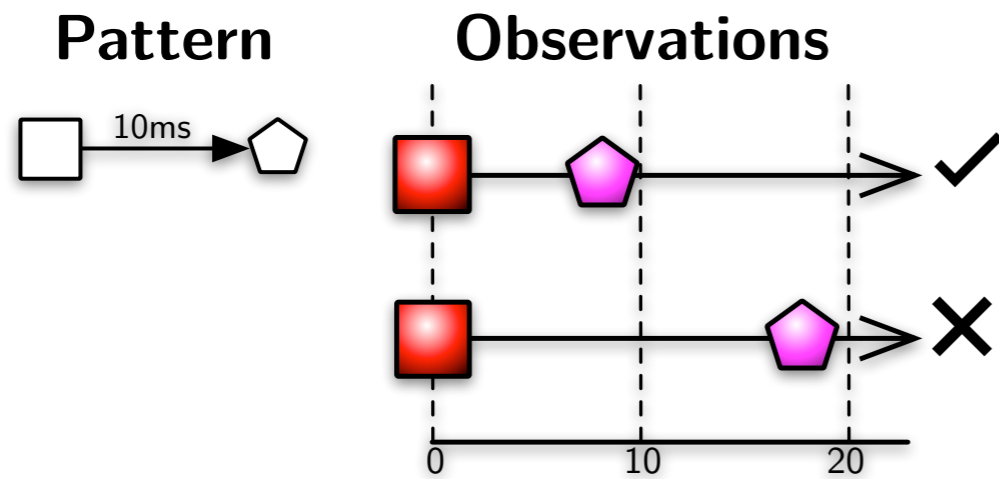
DATA CORRELATION IN RP



<http://reactivex.io>

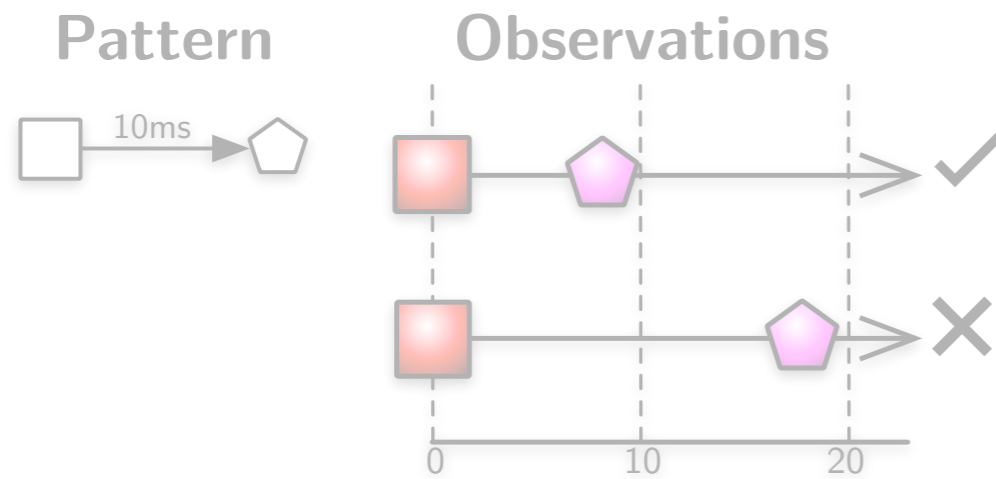
WHERE RP FAILS FAST:

Timing

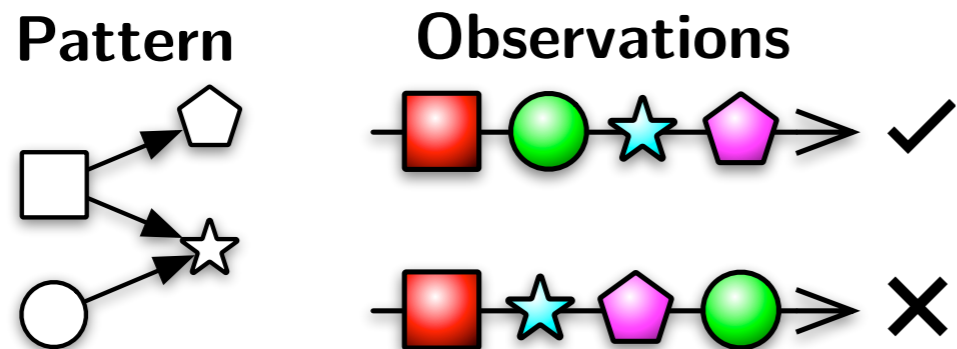


WHERE RP FAILS FAST:

Timing

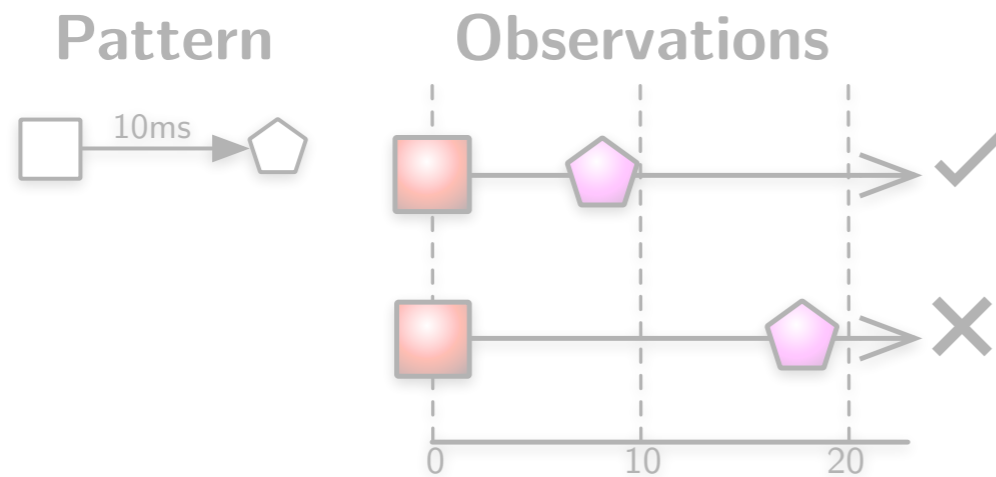


Partial orders

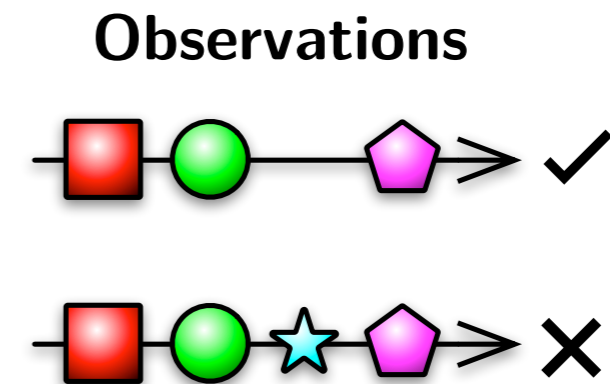


WHERE RP FAILS FAST:

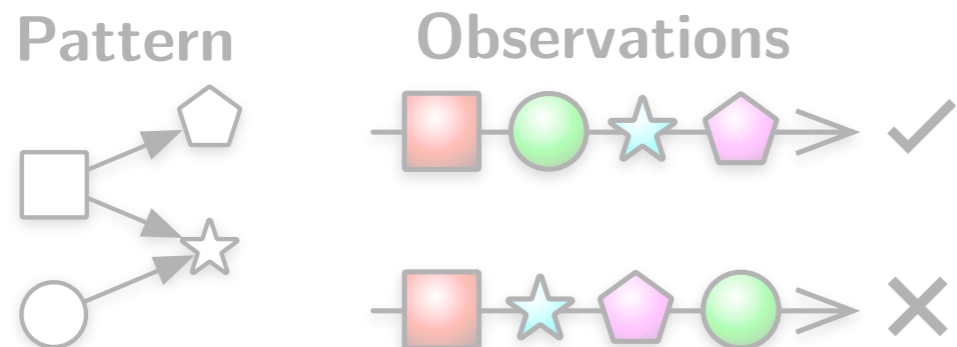
Timing



Absence/negation

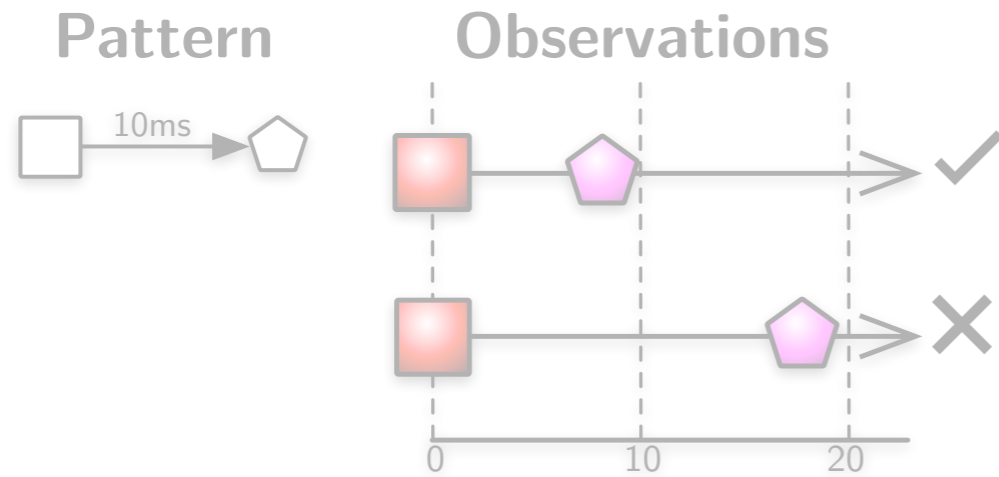


Partial orders

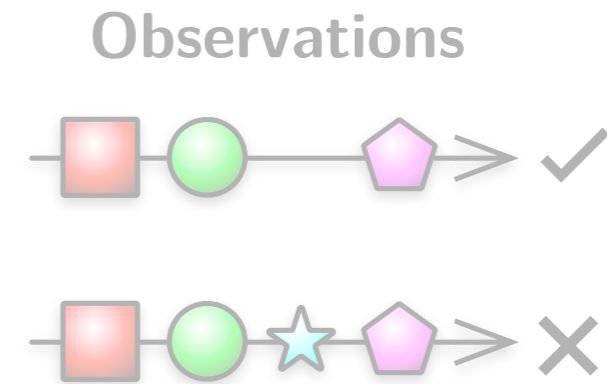


WHERE RP FAILS FAST:

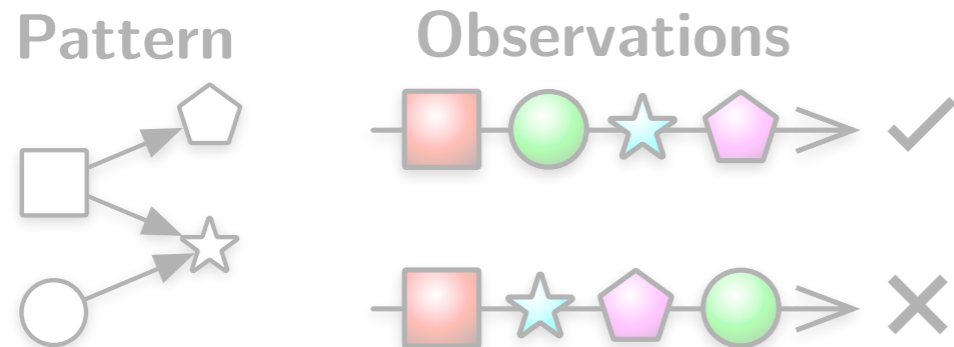
Timing



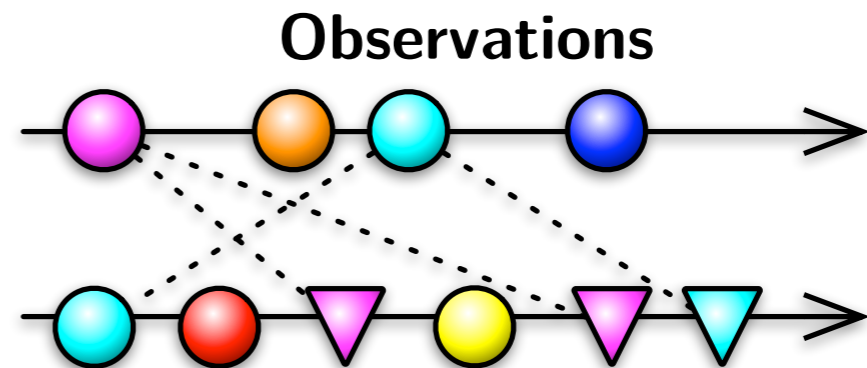
Absence/negation



Partial orders



“Criss-crossing”

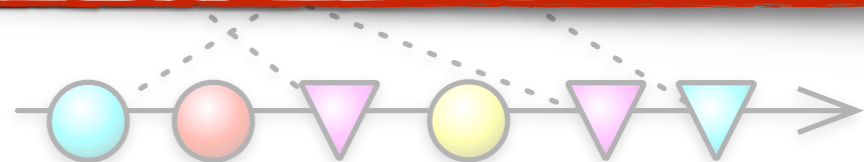
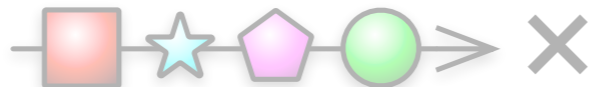
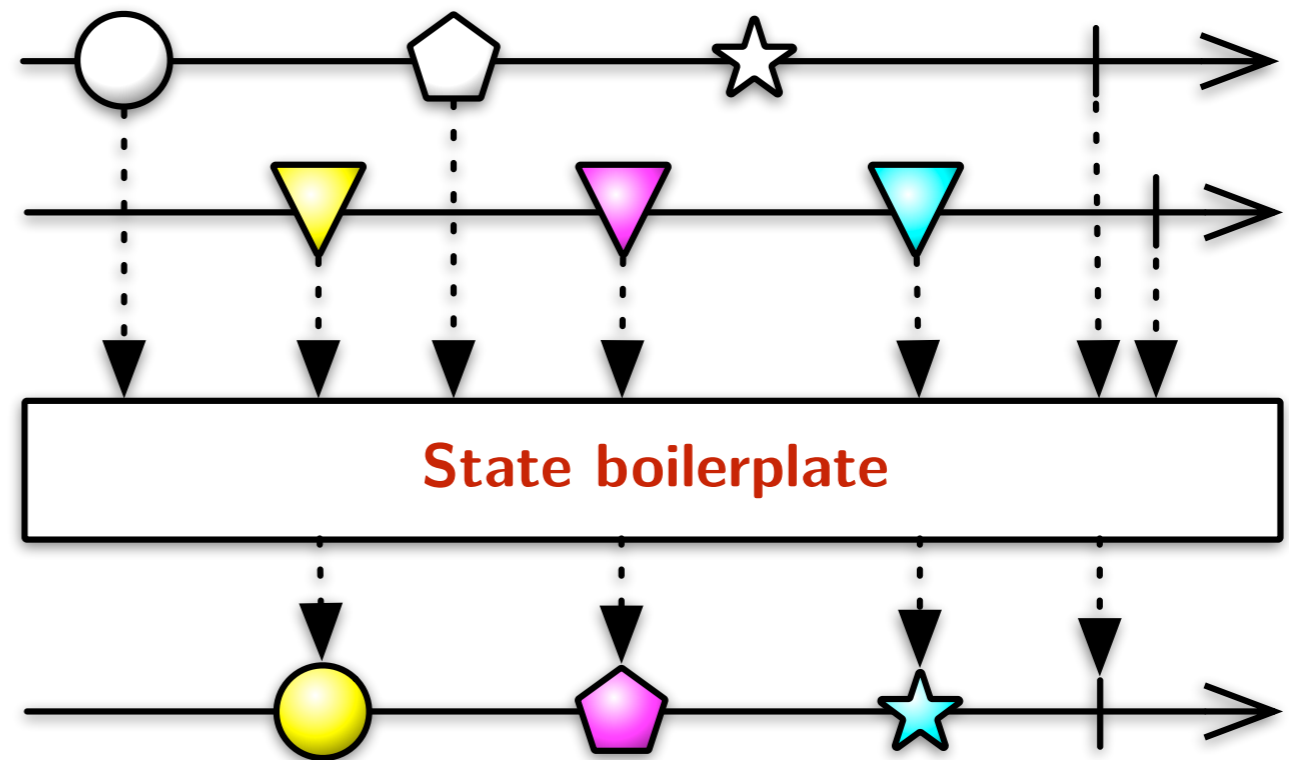


WHERE RP FAILS FAST:

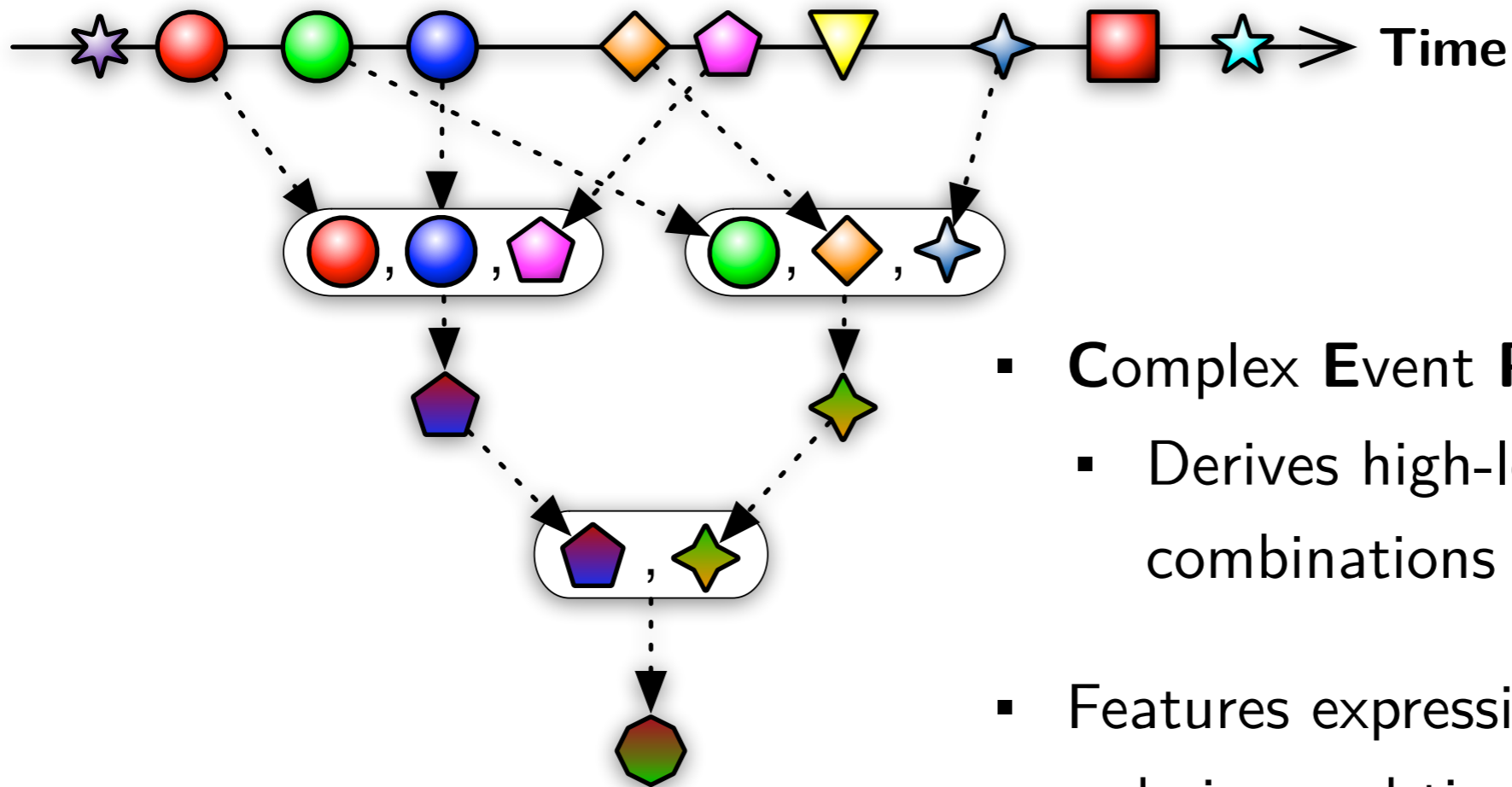
Timing

Absence/negation

- No exposure of arrival orders or timings!
- We need a pattern language!

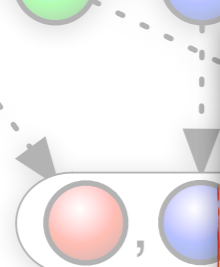


CEP TO THE RESCUE!



- **Complex Event Processing**
 - Derives high-level events from combinations of input events
- Features expressive pattern languages for ordering and timing constraints

CEP TO THE RESCUE!



Why not just combine RP with CEP?

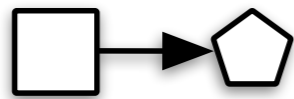
Processing
events from
input events

Features expressive pattern languages for
ordering and timing constraints

VARIABILITY IN CEP

Selection

Pattern



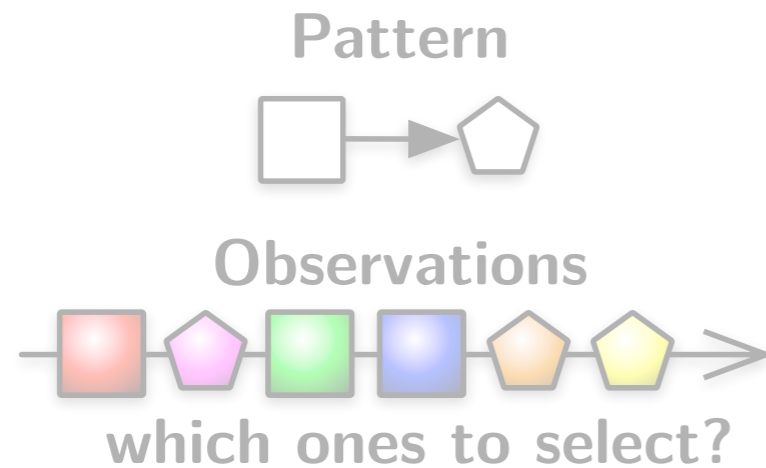
Observations



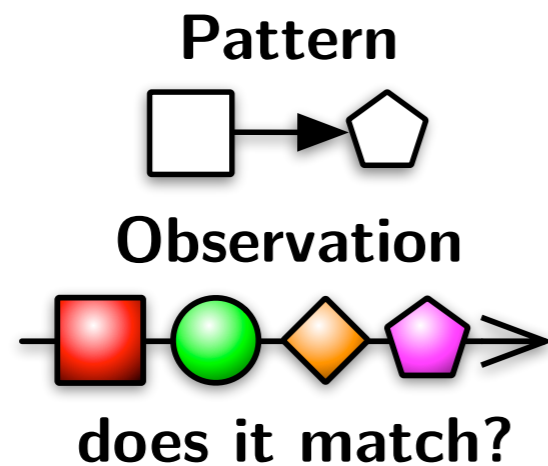
which ones to select?

VARIABILITY IN CEP

Selection

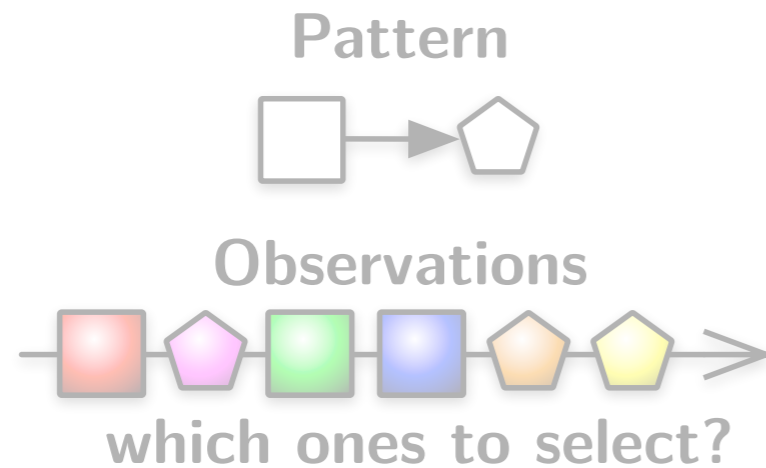


Contiguity

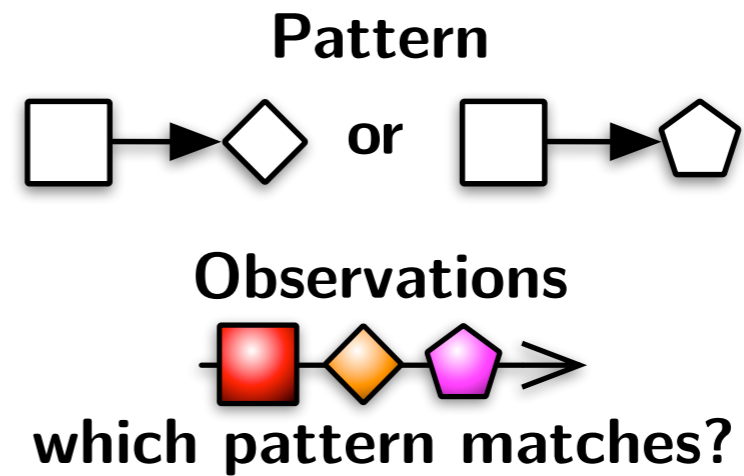


VARIABILITY IN CEP

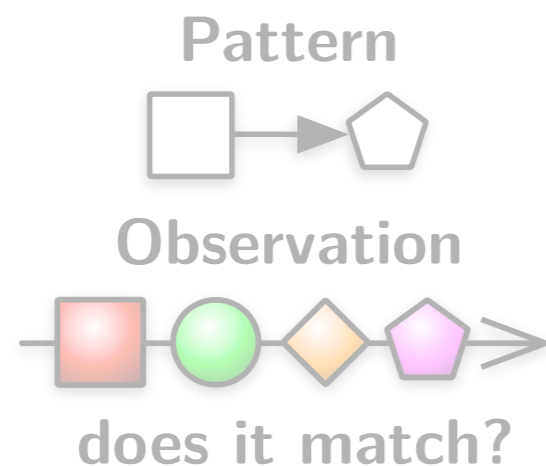
Selection



Consumption

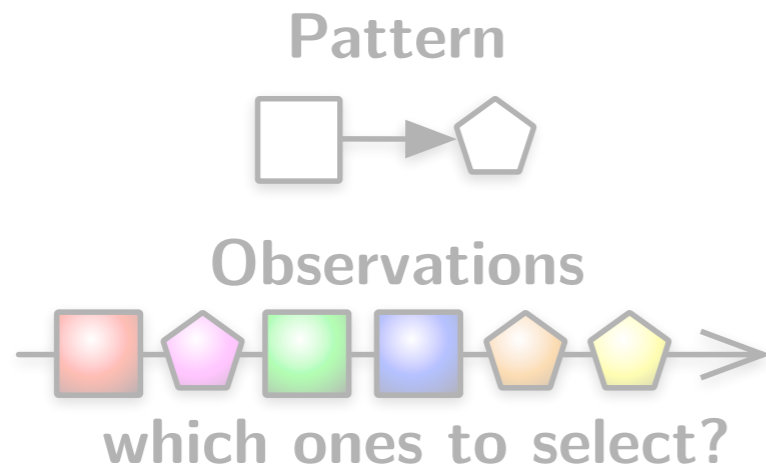


Contiguity

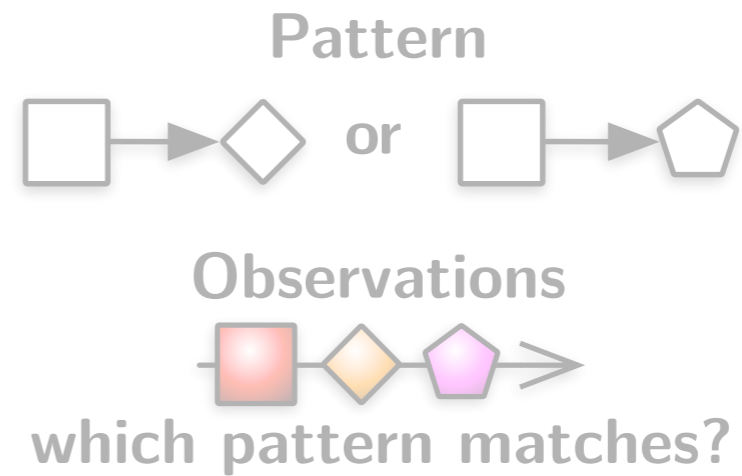


VARIABILITY IN CEP

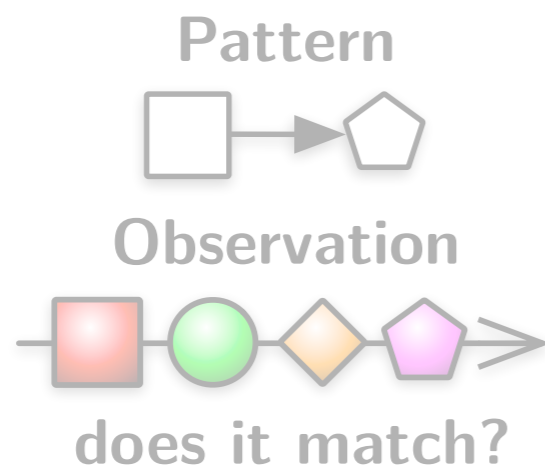
Selection



Consumption



Contiguity

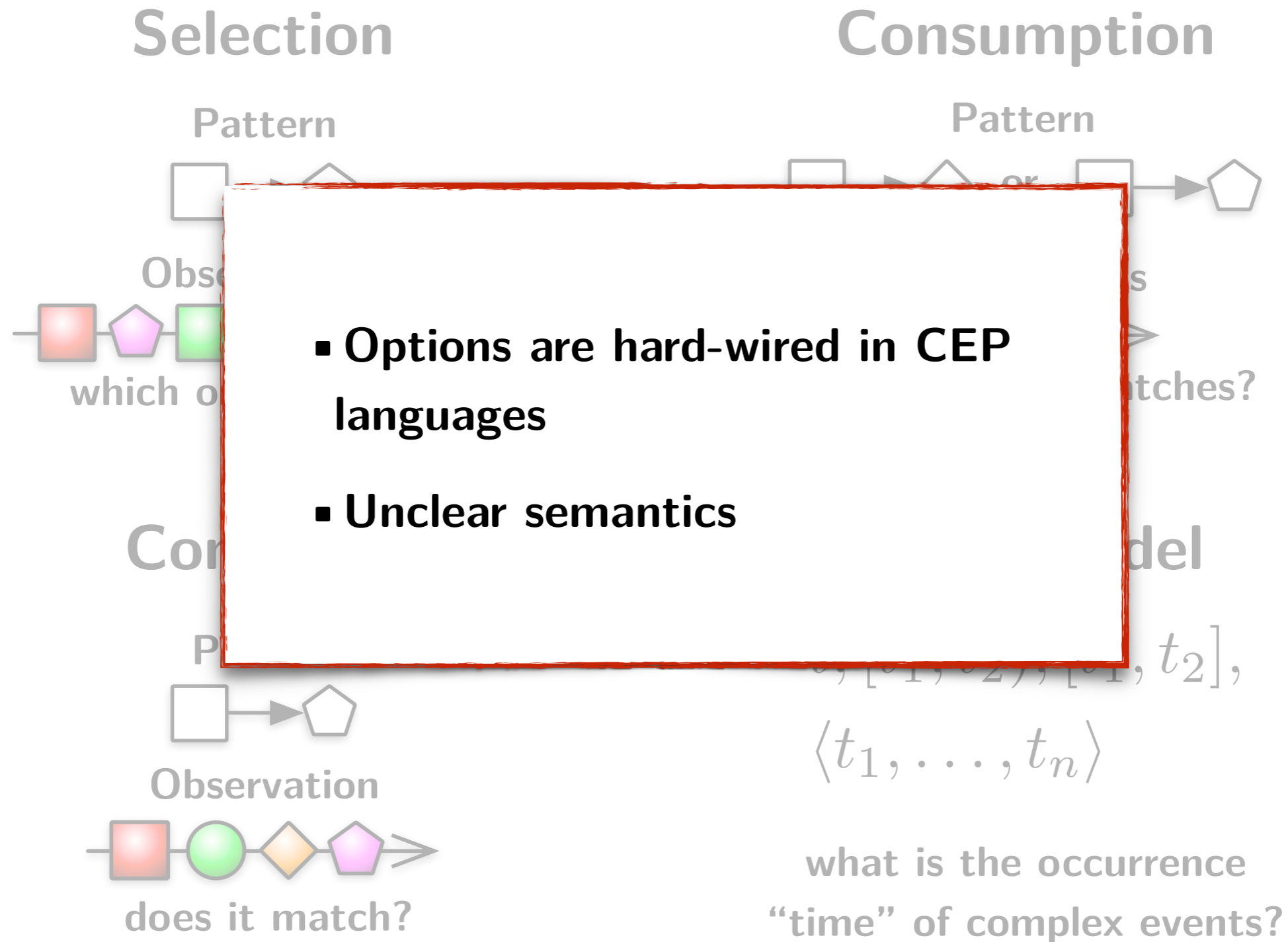


Time Model

t , $[t_1, t_2)$, $[t_1, t_2]$,
 $\langle t_1, \dots, t_n \rangle$

what is the occurrence
“time” of complex events?

VARIABILITY IN CEP



SUMMARY

- **Reactive Programming (RP)**
 - Weak support for correlations by timing and order
 - Strong semantic foundations
- **CEP-style patterns complement RP**
 - Huge variability of features
 - Ambiguous and diverse semantics

CORRL

The Correlation Language



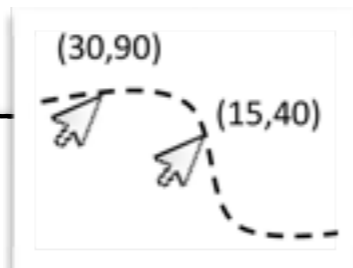
CORRL

The Correlation Language

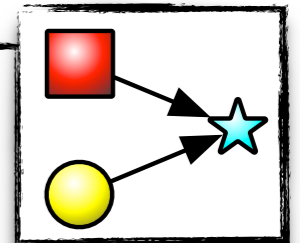
- **CEP-style patterns + Reactive Programming**
 - Embedded DSL (Scala, WIP)
- **Formally specified semantics**
 - Aim for maximal expressivity
 - Support the semantic variability
 - State-machine-based

WIP LANGUAGE DESIGN

```
await
  down:MouseDown
  on down ->
    move:MouseMove
  unless evt:MouseUp
  yield Drag(move.x, move.y)
```



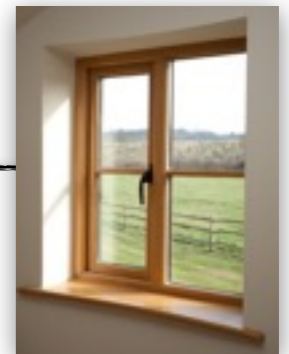
```
await
  down:MouseDown
  & key:KeyDown.
  key.code == SHIFT
  on down & key ->
    move:MouseMove
  unless evt:MouseUp | evt:KeyUp
  yield Drag(move.x, move.y)
```



```
await
  down:MouseDown
  on down ->
    last dr:Drag.
    on dr -> move:MouseMove
  unless evt:MouseUp
    | time(move)-time(dr) > 0.2s
  yield Drag(move.x, move.y)
```



```
await
  down:MouseDown
  on down ->
    move:MouseMove.
    move.y == max(MouseMove.y, 1ms)
  unless evt:MouseUp
  yield Spike(move.x, move.y)
```



SEMANTICS

await

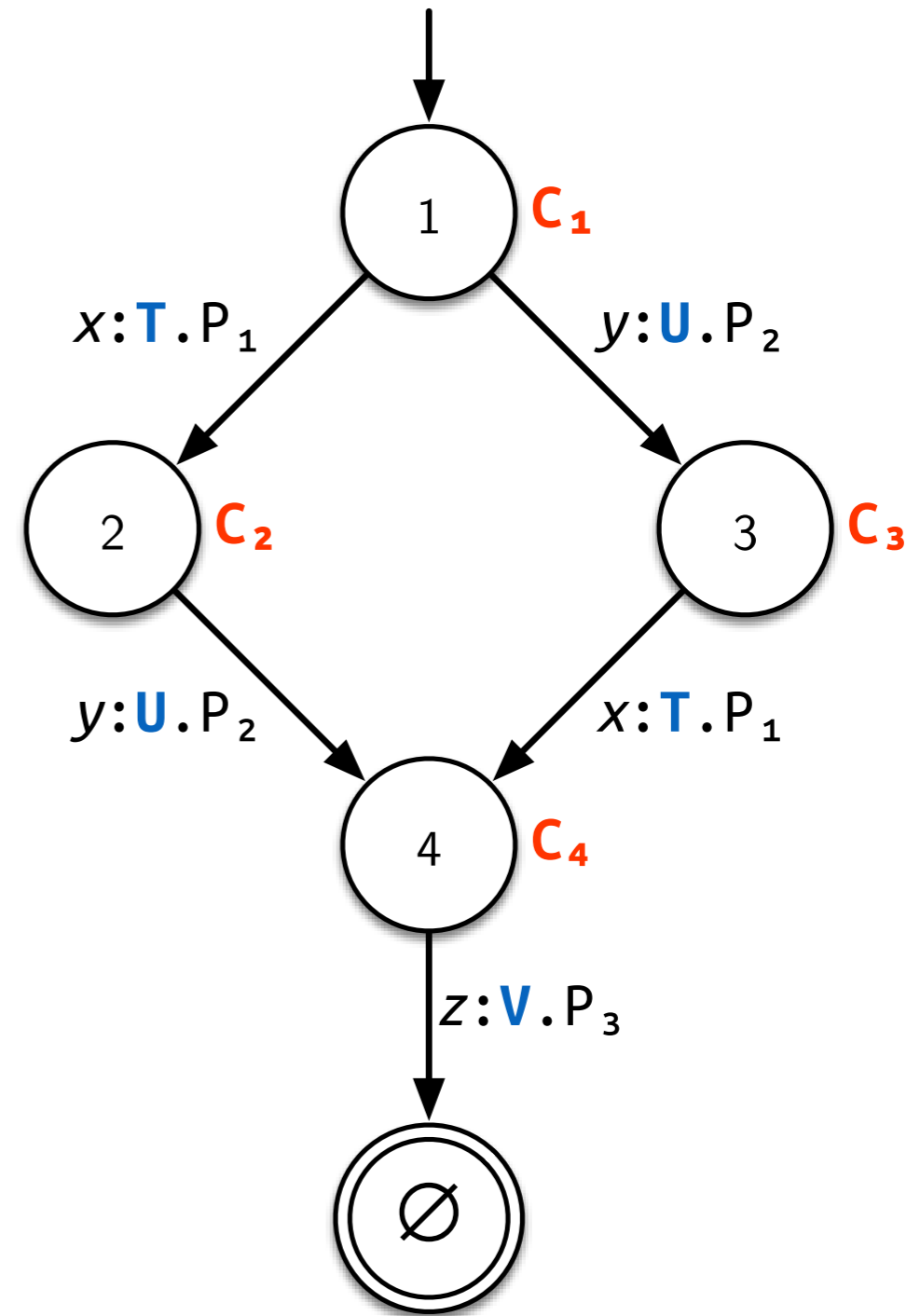
$x:T. P_1(x) \ \& \ y:U. P_2(y)$

on $x \ \& \ y \ \rightarrow$

$z:V. P_3(x,y,z) \ \text{unless} \ K_3(x,y,z)$

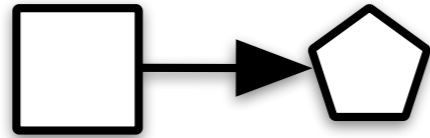
unless $K_0 \mid K_1(x) \mid K_2(y)$

yield $W(e(x,y,z))$

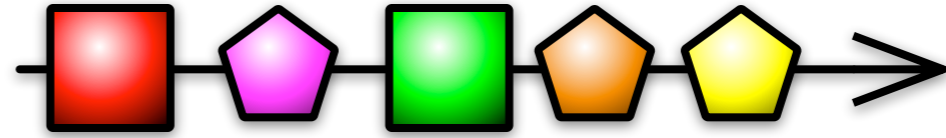


HANDLING VARIABILITY

Pattern

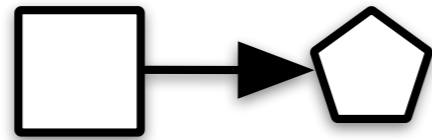


Observations

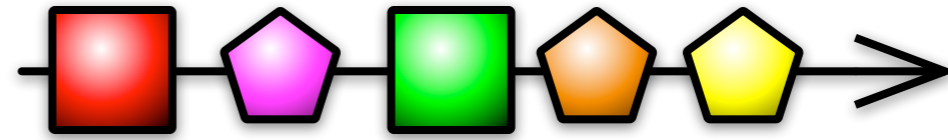


HANDLING VARIABILITY

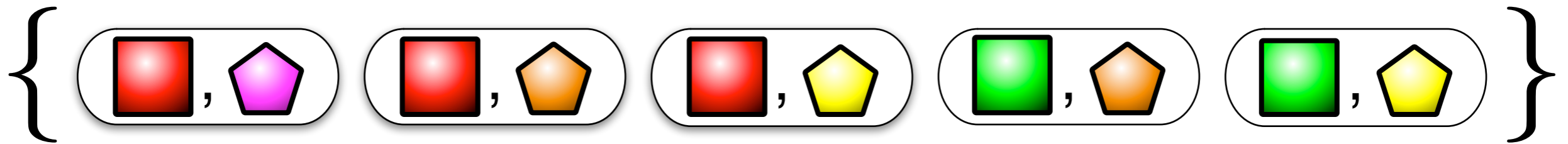
Pattern



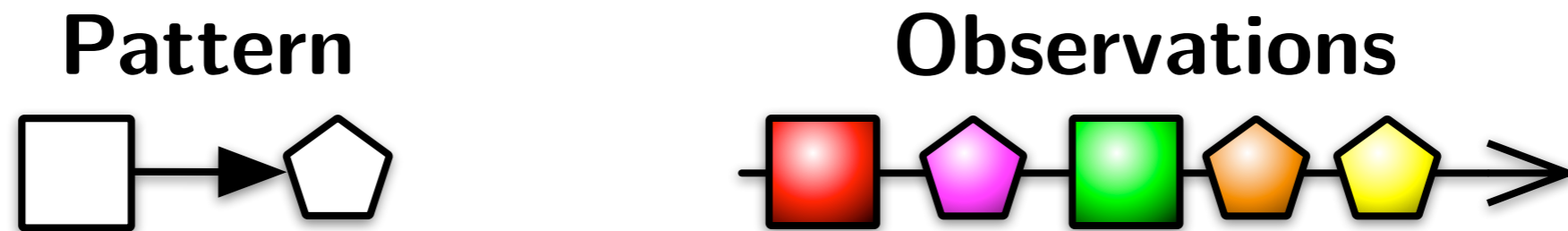
Observations



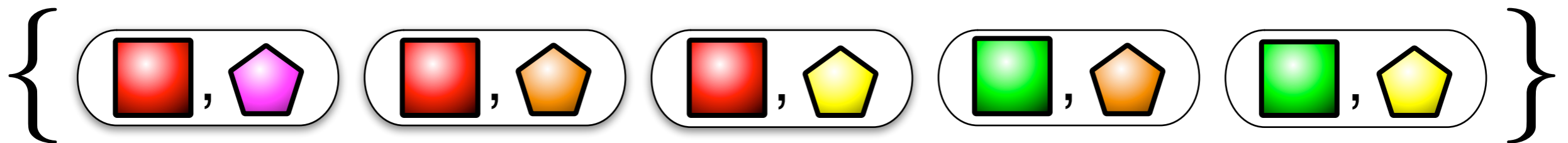
Matches



HANDLING VARIABILITY

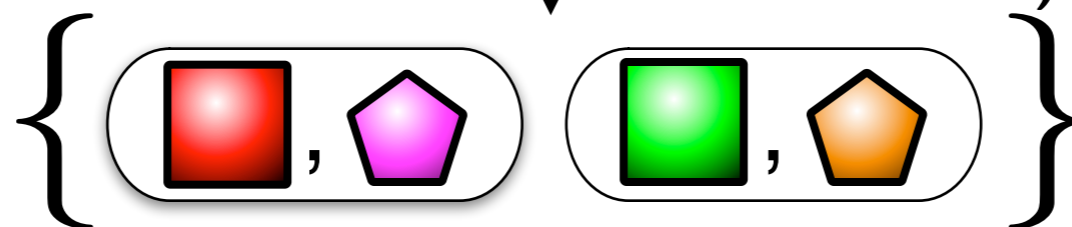


Matches



Cut

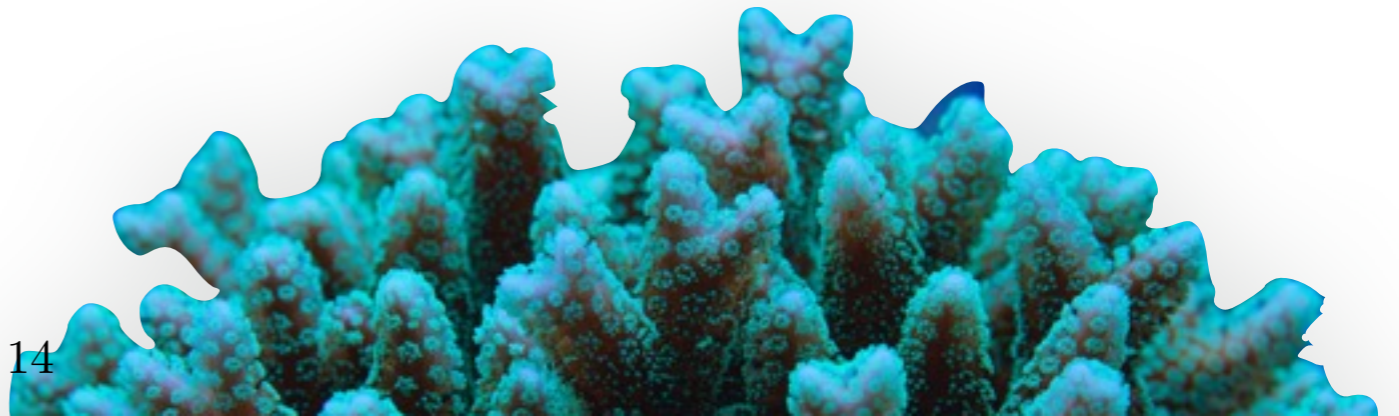
(e.g. first-received semantics)



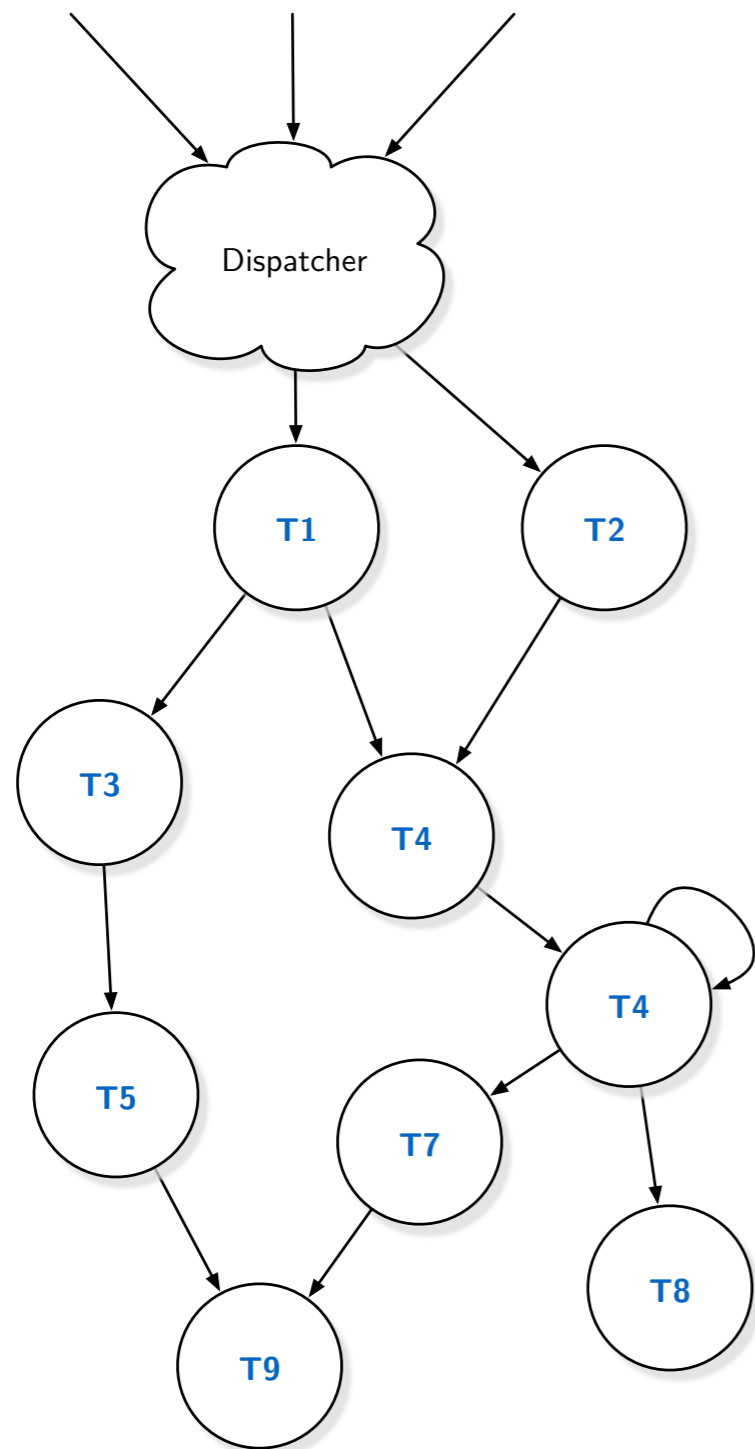
CORRL

Summary and Outlook

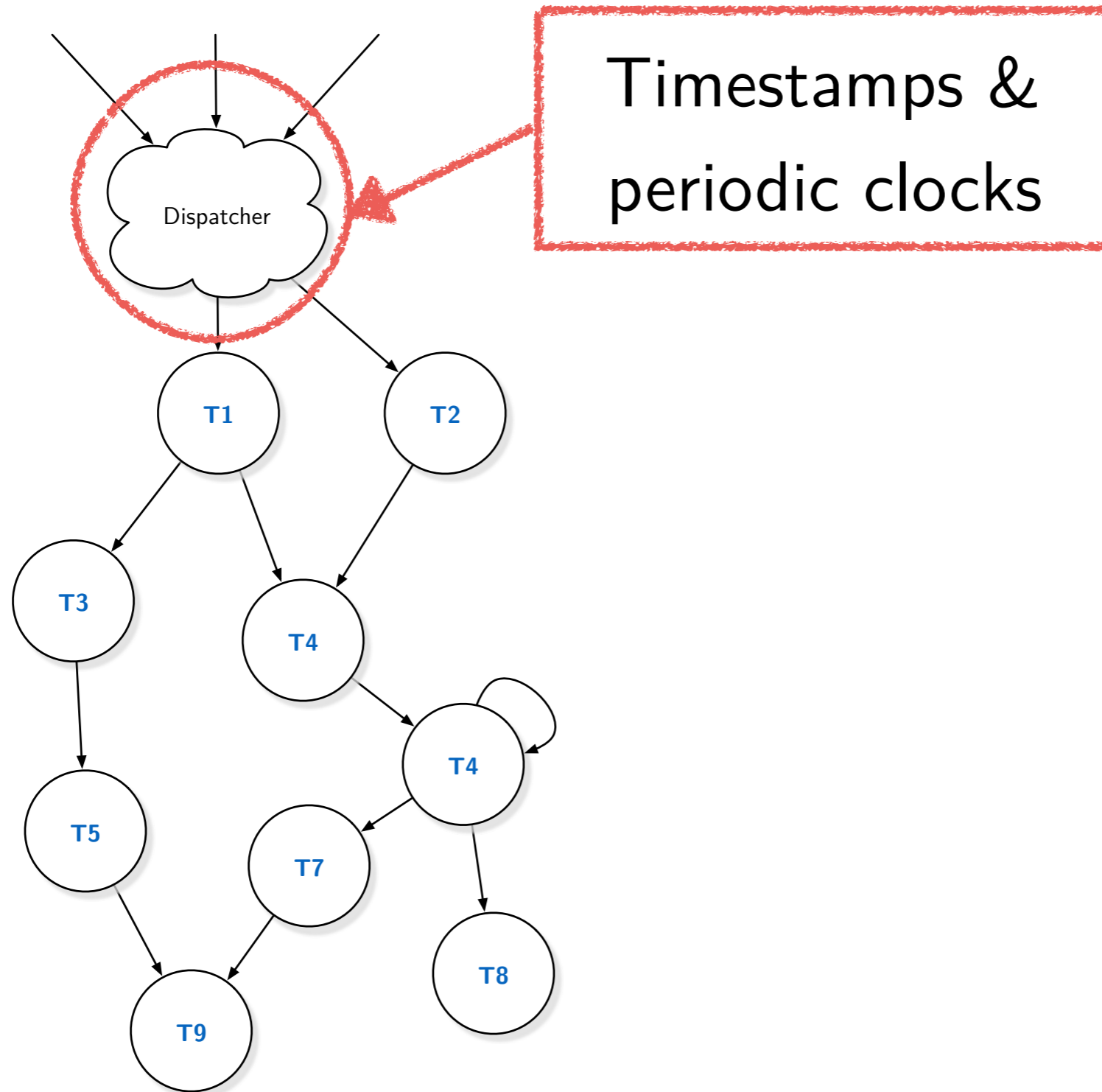
- **Reactive language with expressive correlation patterns**
 - Transformations, Aggregations, Windows, Timing, Partial Orders
- **Which cut functions are efficiently computable?**
 - “No regrets” vs. retraction
- **Explore connection to coordination/
synchronization**



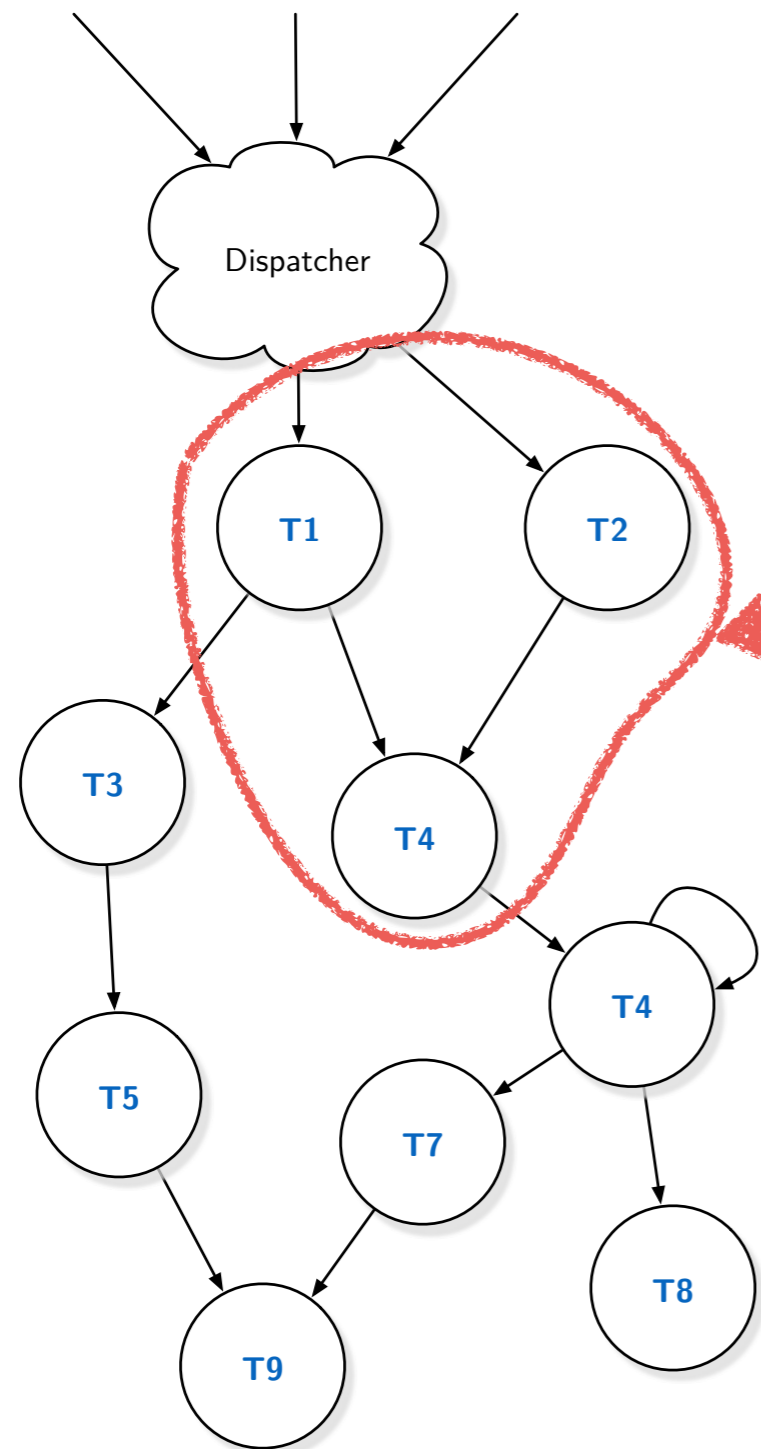
AUTOMATA NETWORK



AUTOMATA NETWORK

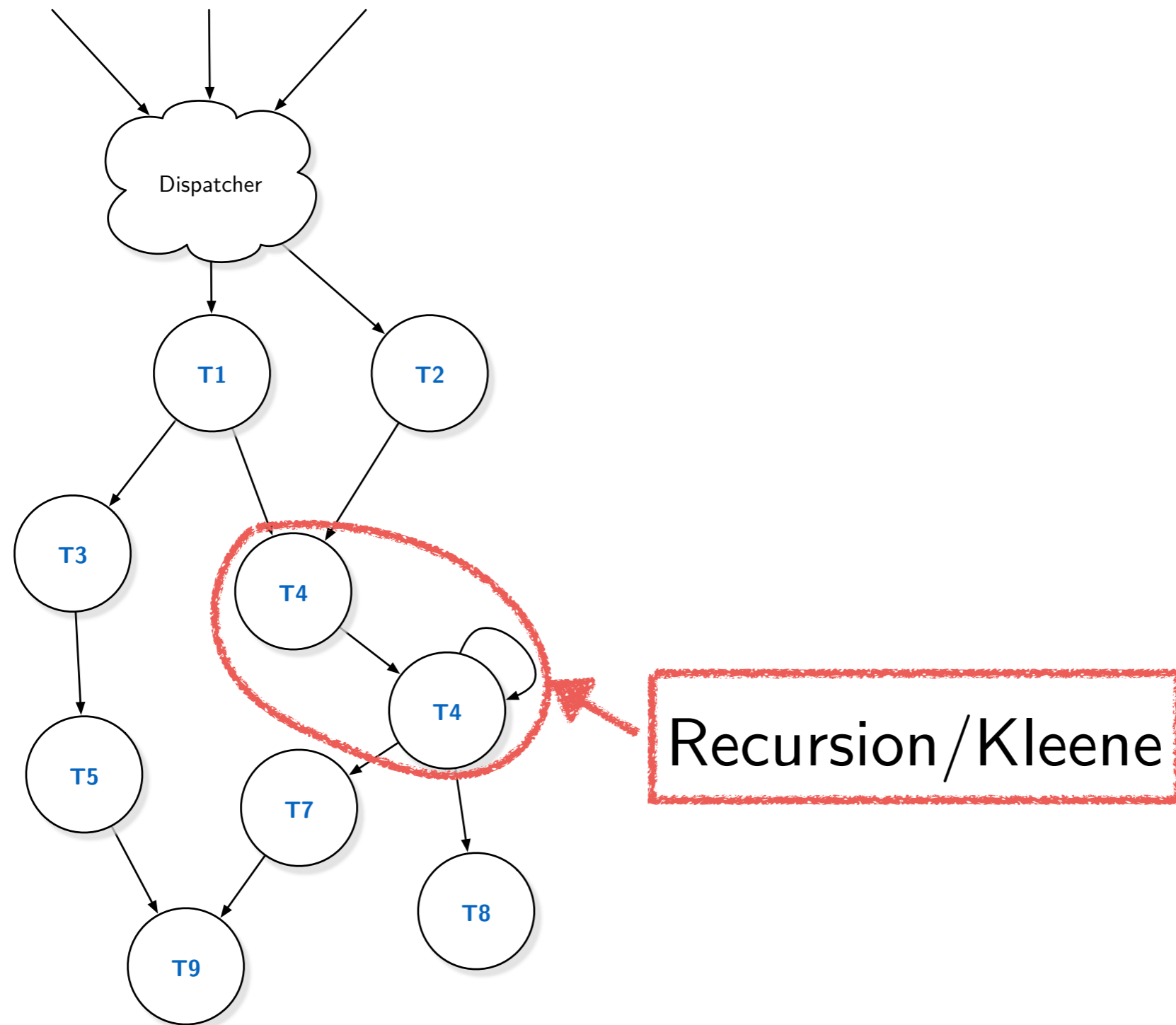


AUTOMATA NETWORK

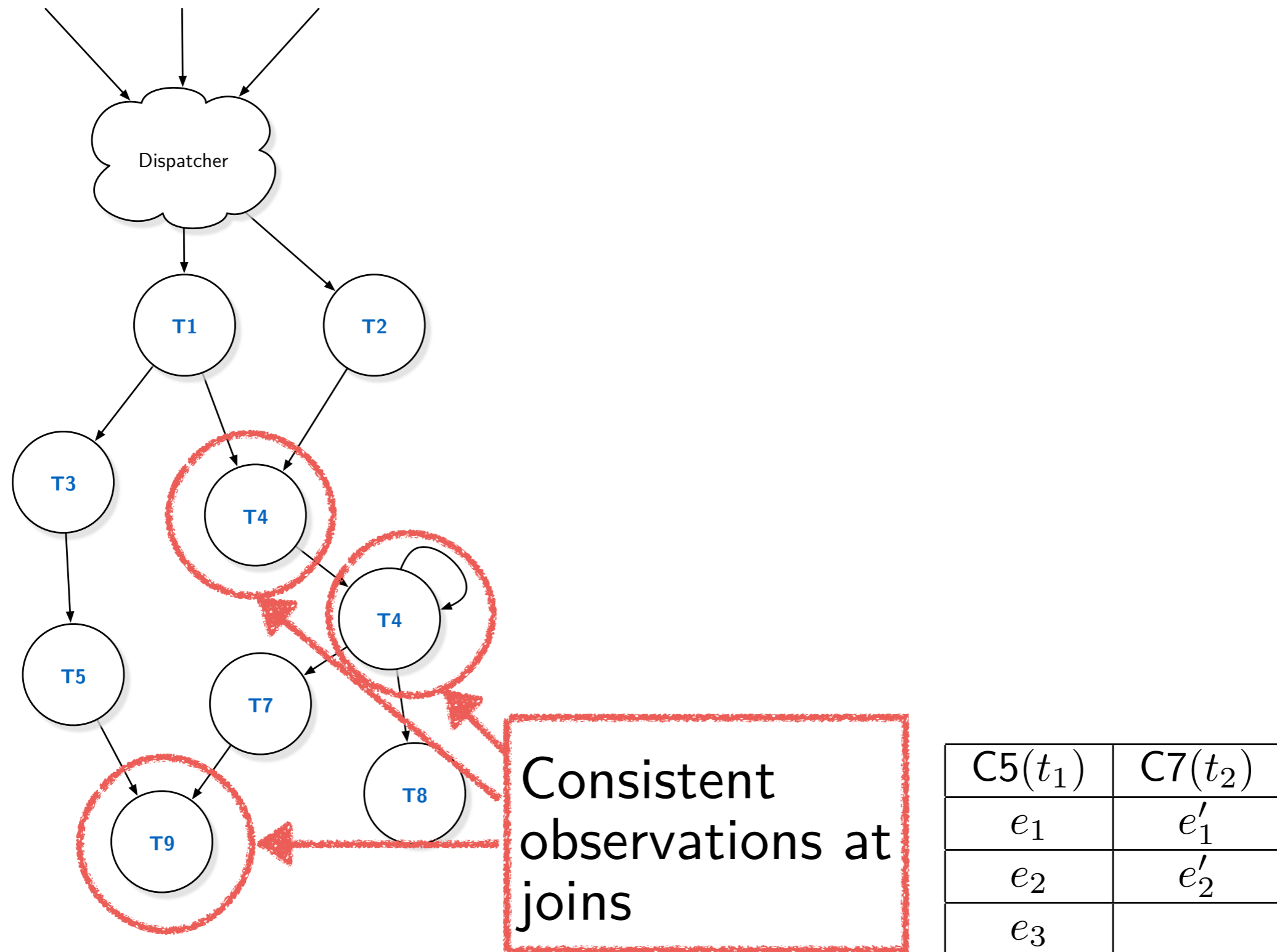


Complex events:
 $C1(x) \ \& \ C2(y) \Rightarrow C4(x+y)$

AUTOMATA NETWORK



AUTOMATA NETWORK



SEMANTICS

await

$x:T. P_1(x) \ \& \ y:U. P_2(y)$

on $x \ \& \ y \rightarrow$

$z:V. P_3(x,y,z) \ \text{unless} \ K_3(x,y,z)$

unless $K_0 \mid K_1(x) \mid K_2(y)$

yield $w(e(x,y,z))$

SEMANTICS

```
await
  x:T. P1(x) & y:U. P2(y)
  on x & y ->
    z:V. P3(x,y,z) unless K3(x,y,z)
  unless K0 | K1(x) | K2(y)
  yield W(e(x,y,z))
```

$v_1 = T(\dots)$

fork!

```
await
  y:U. P2(y)
  on y ->
    z:V. P3(v1,y,z) unless K3(v1,y,z)
  unless K0 | K1(v1) | K2(y)
  yield W(e(v1,y,z))
```

SEMANTICS

```
await
  x:T. P1(x) & y:U. P2(y)
  on x & y ->
    z:V. P3(x,y,z) unless K3(x,y,z)
  unless K0 | K1(x) | K2(y)
  yield W(e(x,y,z))
```

$v_1 = T(\dots)$

fork!

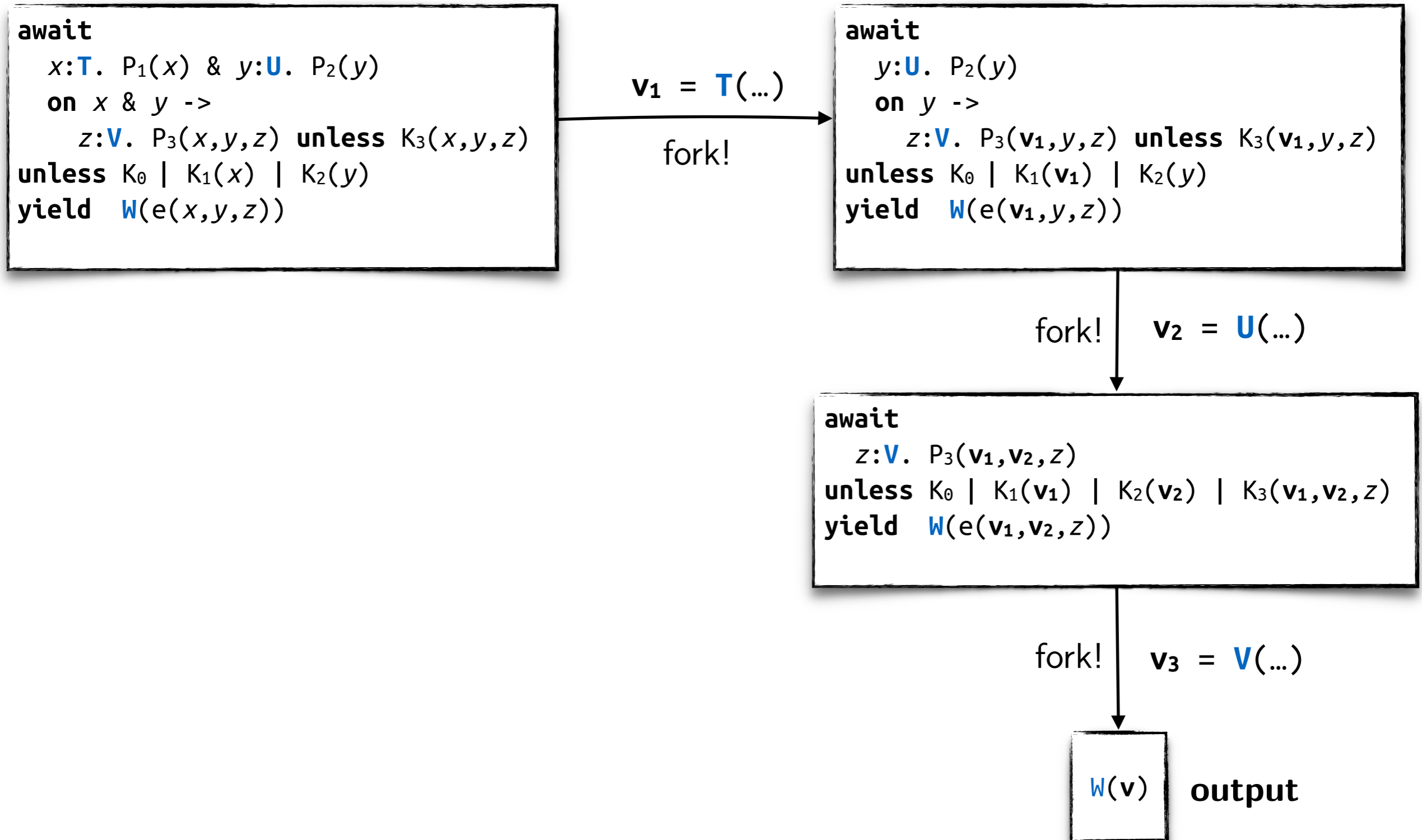
```
await
  y:U. P2(y)
  on y ->
    z:V. P3(v1,y,z) unless K3(v1,y,z)
  unless K0 | K1(v1) | K2(y)
  yield W(e(v1,y,z))
```

fork!

$v_2 = U(\dots)$

```
await
  z:V. P3(v1,v2,z)
  unless K0 | K1(v1) | K2(v2) | K3(v1,v2,z)
  yield W(e(v1,v2,z))
```

SEMANTICS



SEMANTICS

```
await
  x:T. P1(x) & y:U. P2(y)
  on x & y ->
    z:V. P3(x,y,z) unless K3(x,y,z)
  unless K0 | K1(x) | K2(y)
  yield W(e(x,y,z))
```

$v_1 = T(\dots)$

fork!

```
await
  y:U. P2(y)
  on y ->
    z:V. P3(v1,y,z) unless K3(v1,y,z)
  unless K0 | K1(v1) | K2(y)
  yield W(e(v1,y,z))
```

fork!

$v_2 = U(\dots)$

```
await
  z:V. P3(v1,v2,z)
  unless K0 | K1(v1) | K2(v2) | K3(v1,v2,z)
  yield W(e(v1,v2,z))
```

fork!

$v_3 = V(\dots)$

W(v)

output

**Fork on every
reduction step,
maximal selectivity**

JOIN PATTERNS

```
//initialize buffer with the first frame  
srcs⟨frame⟩ if frame.id == 0 ▷  
  buffer⟨frame :: Nil⟩ || last⟨0⟩  
  
//append to buffer in the order of the id  
srcs⟨frame⟩ & buffer⟨xs⟩ & last⟨n⟩  
  if frame.id == n + 1 ▷  
    buffer⟨xs.frame⟩ || last⟨frame.id⟩  
  
//output buffer in chunks  
buffer⟨fs⟩ if fs.length ≥ N ▷  
  buffer⟨fs.drop(N)⟩ || out⟨fs.take(N)⟩
```

Synchronization = Correlation!